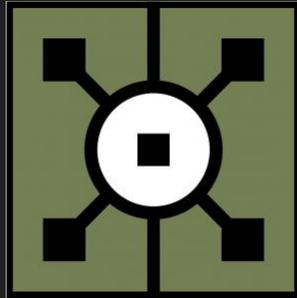


Using Arduino with TouchDesigner

The NODE Institute SS23



Workshop outline

1. Introduction
2. Arduino Ecosystem, Sensors/Actuators
3. Programming with Arduino
4. Integrating Arduino and TouchDesigner
5. Q&A, etc.

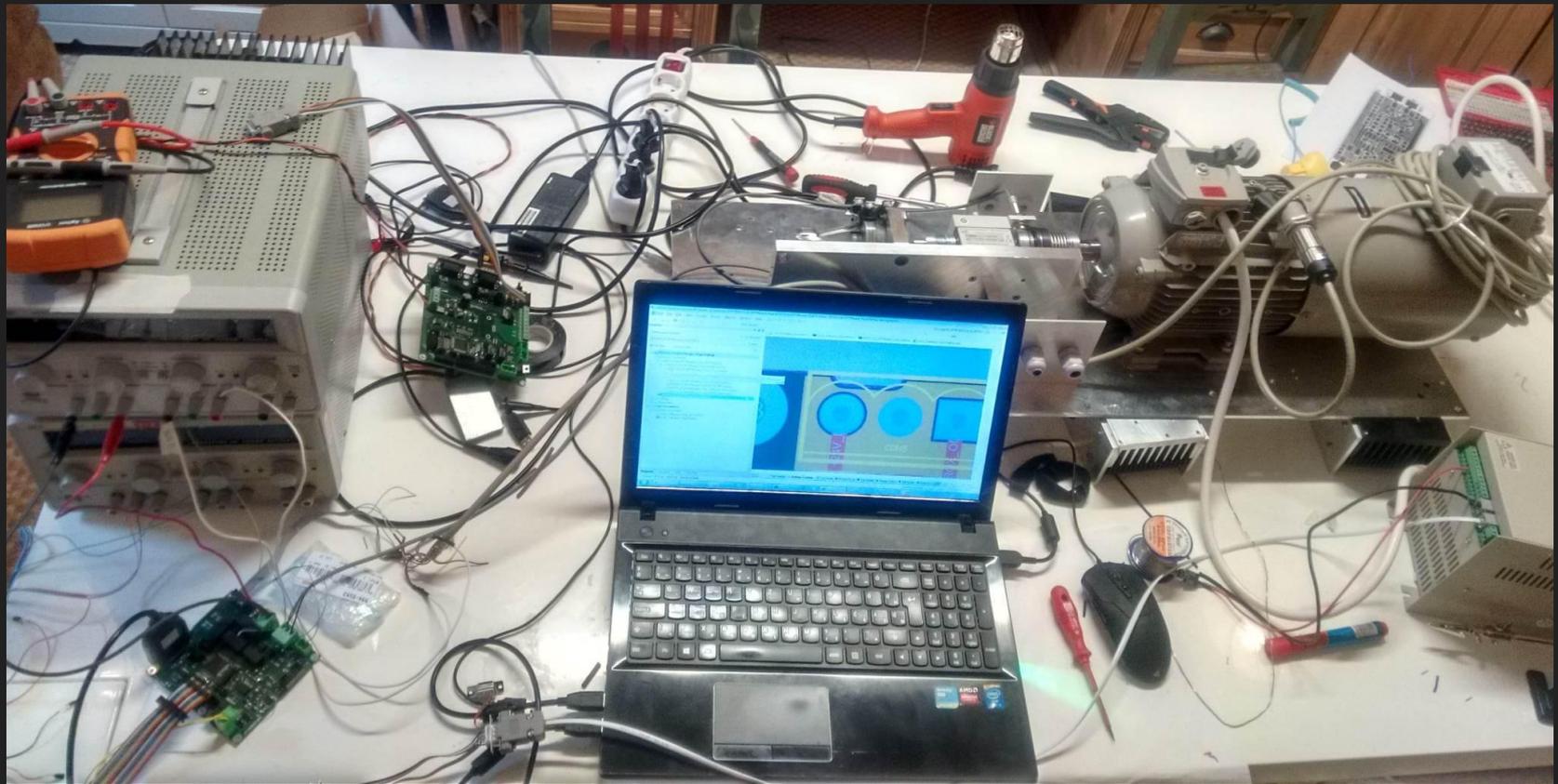
Daniel Molnar (Function Store) - Dan



- ❖ Born in **Budapest, Hungary**;
Living in **Berlin, Germany**
- ❖ Masters in Electrical Engineering (2014)
- ❖ Software Developer (2014 - 2021)
 - ~5 years as Embedded Engineer
 - ~2.5 years as Audio/DSP Engineer
- ❖ ...
- ❖ TouchDesigner Developer (2022 -)

Embedded Life

- ❖ Various automotive and consumer electronics projects
 - **Automotive:** brake motor tester system, capacitance tester systems, CAN/modbus controlled relay boxes, test tower monitoring web interface, participation in clutch controller tester development, participation in dashboard display tester development
 - **Consumer electronics:** stereographic DSLR camera control system, professional GoPro operator accessory, iPhone accessory bootloader
 - **Other:** solar panel cleaning robot, smart-metering research and development, pipe leakage monitoring system, participation in railway diagnostics system development
- ❖ Custom hardware and software (firmware) stack
- ❖ Embedded OS
- ❖ Radio communication
- ❖ Robust systems



The desk of an Embedded Engineer

Creative Life

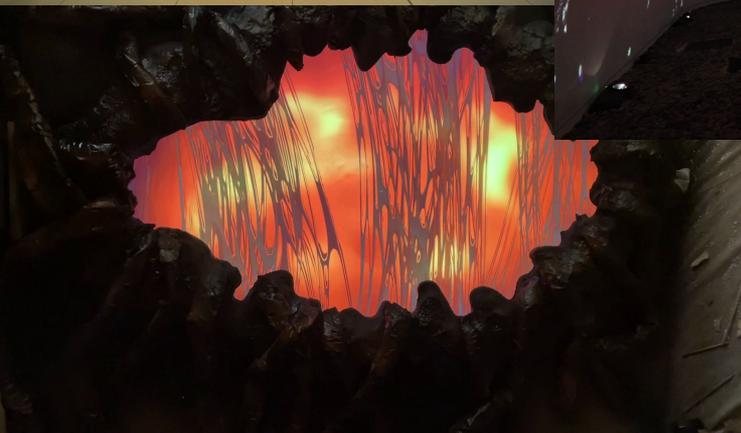
- ❖ Music as hobby (guitar/bass)
 - Made visuals in After Effects and Winamp's Milkdrop2



- ❖ Discovered TouchDesigner in 2020
- ❖ TouchDesigner Developer (2022 -)
 - Interactive installations, audiovisuals, system design
 - Tool development ([YouTube/Patreon](#))



The desk of a TD developer



Inspiration

[Kyle Duffield - lots of stuff](#)

[Nima Gazestani - Custom Controller](#)

[Nima Gazestani - RFID interaction](#)

[Irina Petrova - WiFi enabled proximity sensors](#)

[Steven Benton - LeapMotion + Servo Motor](#)

[Me \(Function Store\) - Fitness Activity](#)

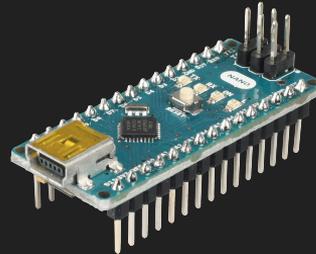
Arduino Ecosystem

- Open-source electronics platform
 - Tool for students at the Interaction Design Institute Ivrea in Ivrea, Italy, 2005
 - Hardware and Software for making digital devices and interactive objects
- Aimed at hobbyists
 - Goal: lowering the barrier of entry to electronics and programming
- Professional prototyping
 - Quick and inexpensive way to test an idea
- Great community
 - Countless forums, blogs, tutorials
 - Open-source

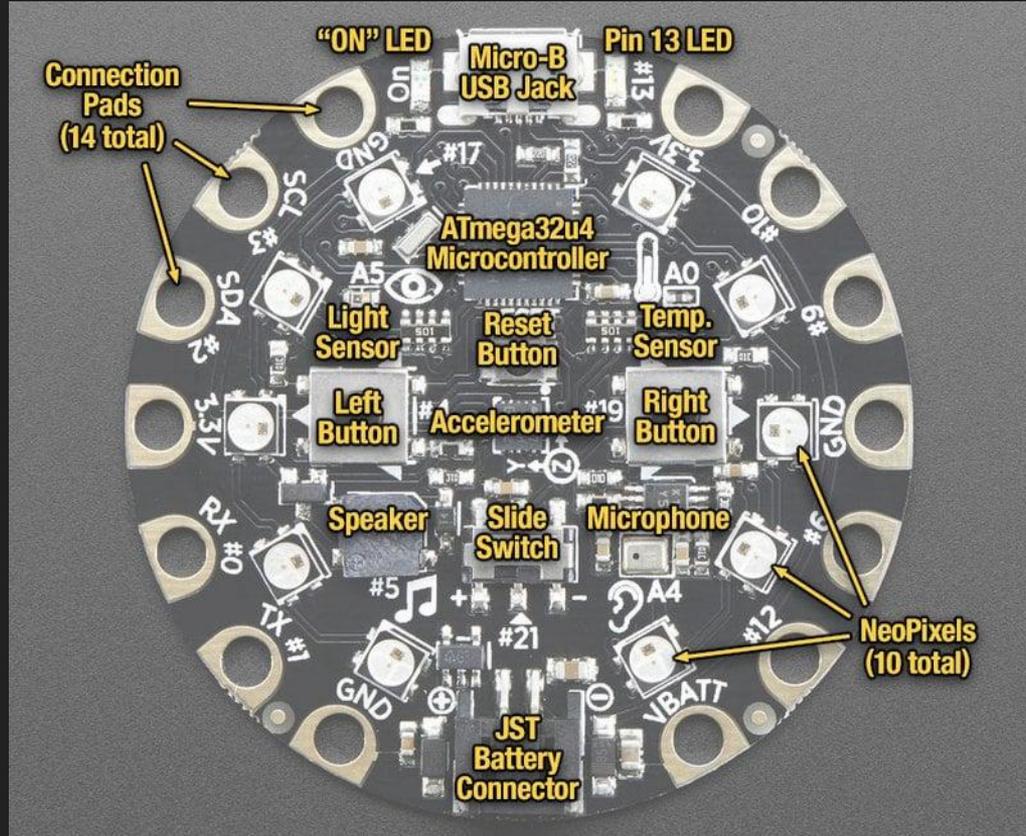


Hardware

- Lots of different boards
 - Usually based around an Atmel microcontroller, varying amounts of flash memory, pins, and features
 - “Arduino-compatible” boards
 - Such as Adafruit Circuit Playground
- Shields (addon boards)
 - Extra functionality modules
 - Stackable
- Plethora of sensors/actuators

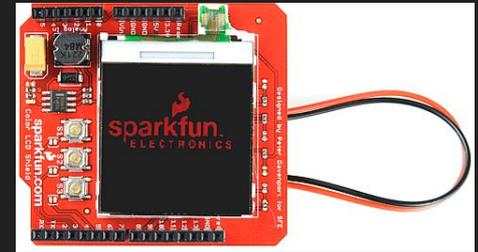
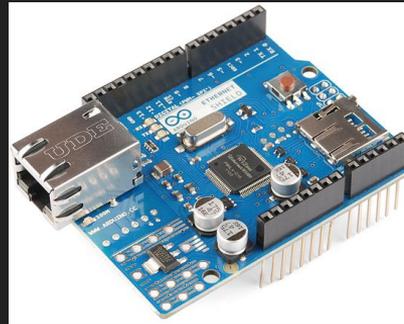
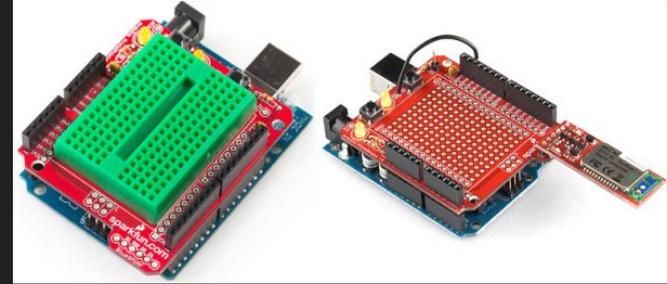


Adafruit Circuit Playground (classic)



Shields

- Breadboard
- Ethernet
- Motor
- WiFi
- SD Card
- GPS
- GSM
- LCD Screen
- ...



Sensors

Basically anything that you can measure physically

- Temperature*
- Humidity
- Ultrasonic distance
- Infrared motion
- Light sensor*
- Accelerometer*
- Gyroscope
- Soil moisture
- Capacitive touch*
- Microphone*
- Magnetic Hall
- Buttons
- Potentiometers
- etc

Often you can find “Arduino sensors” designed with the hobbyist market in mind:

- Ease of use with Arduino boards
- Standardized connector
- Conditioning resistors/capacitors/amplifiers
- Sample code / Library
- Eg.: Grove system by Seeed Studio

Motion sensors

- PIR Motion Sensor

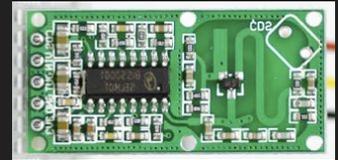
- Heat energy from body -> IR radiation
- Watch out for other IR sources (sun)
- ~10 bucks, 6 meters range 110°x70° (depends)
- Good for triggering events in an installation space
- Outputs low/high

- Microwave Radar Motion Sensor

- Doppler effect
- Does not rely on heat
- Generally bigger range, can go through walls

- Ultrasonic Distance Sensor

- Time-of-flight principle (time between emitting and receiving an ultrasonic wave)
- Sound reflection
- 4m range
- [Usage example](#)

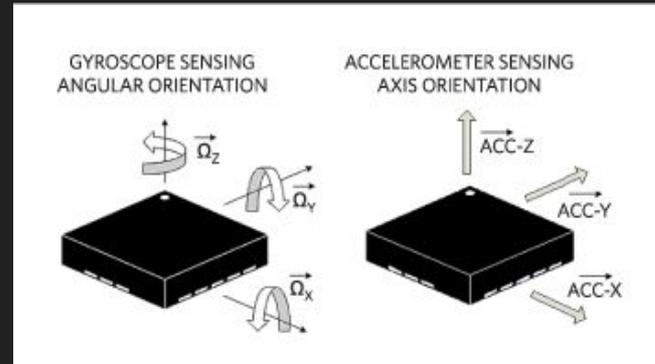


Accelerometer, Gyroscope

- Gyroscope measures the rotation rate around a specific axis (roll, pitch, yaw), helps maintain orientation
 - Steadycam
- Accelerometer measures the rate of change of velocity along XYZ axis.

Gravity is always present!

- Integrating acceleration data over time, velocity can be determined
 - Drift over time!
- Can derive roll and pitch (see later)
- Gesture sensing, indoor navigation



Actuators

Interacting with the physical world:

- Servo motors
- DC motors
- Stepper motors
- Relays
- LEDs
- Piezo buzzers
- Solenoids
- Pumps and valves
- ...

Similar to sensors you can find “Arduino compatible” actuators designed with the hobbyist market in mind.

Brands to look out for:

- Adafruit
- Sparkfun
- Grove

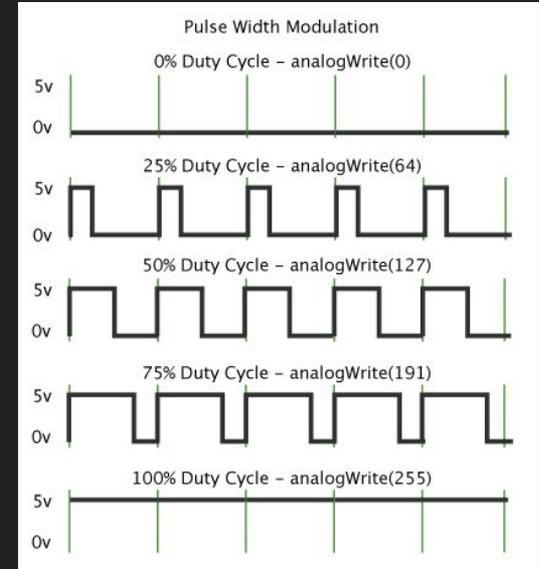
Controlled Motion Devices

| <u>AC/DC Motors</u> | <u>Stepper Motors</u> | <u>Servo Motors</u> |
|--|-------------------------------------|--|
| Simple direction control | Moves in discrete steps | Moves to position - requires feedback |
| Less precise than stepper/servo, needs external feedback | Less accurate, can lose steps | Higher precision |
| High torque, constant at all speeds | High torque at low speed, decreases | ~ torque at wide range of speeds, high speed |
| Cheaper and simpler (without feedback) | Cheaper and easy to control | More complex and expensive |
| Smooth and quiet | Noisy and generate vibration | More smooth and quiet |

Interfaces

How can we communicate with sensors/actuators/other systems?

- **Digital I/O:** reading binary values (HIGH(1) or LOW(0))
- **Analog I/O:** reading voltage of an analog signal (usually 10 bit precision)
- **PWM I/O:** no true analog output but Pulse-Width Modulation can simulate to drive speaker, [control brightness of LED](#) or speed of motor



Serial Interfaces

- UART/"Serial" (Universal Asynchronous Receiver/Transmitter): asynchronous serial communication - computer/GPS/Bluetooth
 - **TX (Transmit)**: This line is used to send data from the UART to another device.
 - **RX (Receive)**: This line is used to receive data sent to the UART from another device.
 - **GND (Ground)**: This line is used as a common ground reference between the two communicating devices.
- SPI (Serial Peripheral Interface): synchronous data transfer to one or more devices over short distances, high speed
 - **SCLK**: Serial Clock (output from master)
 - **MOSI**: Master Out Slave In (data output from master)
 - **MISO**: Master In Slave Out (data output from slave)
 - **SS/CS**: Slave Select (often active low, output from master to indicate that data is being sent)

Serial Interfaces

- **I²C (Inter-Integrated Circuit)**: sync comm of multiple slaves to a master device, simple and efficient, minimal pin requirement
 - **SDA (Serial Data)**: The line for the master and slave to send and receive data.
 - **SCL (Serial Clock)**: The line that carries the clock signal.
- **CAN (Controller Area Network)**: message-based protocol, automotive/industrial equipment

Comparison with Other Microcontrollers

- **Raspberry Pi:** Technically a single-board computer (SBC). More powerful processing capabilities, full operating system for complex software-intensive projects. Less straightforward handling of low-level hardware tasks, more power requirement.
- **ESP Family:** WiFi/BLE capable more powerful microcontrollers, IoT projects. Compatibility with Arduino.
- **Standalone AVR and ARM uC's:** Programmable with Arduino IDE. Lower cost for mass production, more hardware complexity.
- **Commercial uC Boards:** Lots of commercial products like the STM32 series with higher performance and more features, but less beginner-friendly.

Resources

- <https://docs.arduino.cc/learn>
- <https://docs.arduino.cc/built-in-examples>
- <https://projecthub.arduino.cc/>
- <https://www.instructables.com/search/?q=arduino&projects=all>
- <https://www.tinkercad.com/> - simulator
- <https://wokwi.com/> - simulator
- https://github.com/adafruit/Adafruit_CircuitPlayground
- <https://td-olib.org/>
- <https://derivative.ca/community-post/asset/wavetop/67796>